

TECNOLOGIAS 2019

Multirobot System for Marine Environments

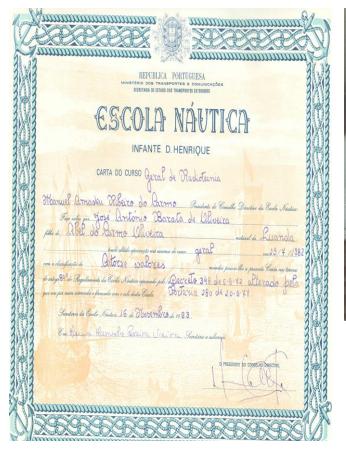
José Barata





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UNIVERSIDADE NOVA DE LISBOA

Some Background





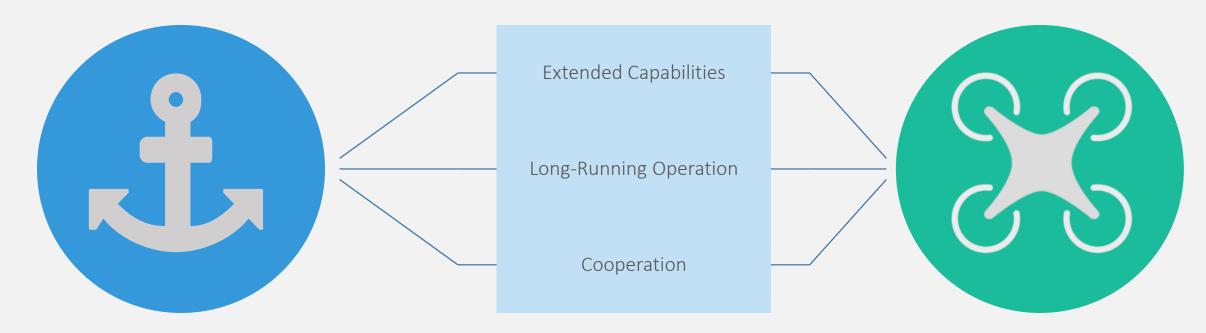






Concept

USV – Unmanned Surface Vehicle UAV – Unmanned Aerial Vehicle



Concept





USV

This vehicle ensures long-range transport and in adverse weather conditions



UAV

Extends the team's perceptional capabilities. Able to land in the water



Long-Running Operations

Exploring the greater energy autonomy of the Surface Vehicle the team can do longer missions



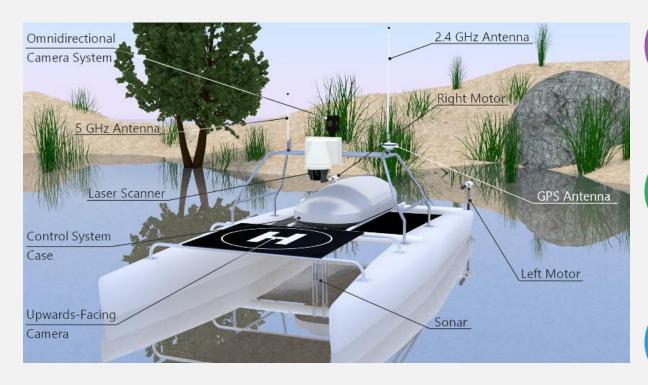
Extended Capabilities

Cooperation between vehicles provides better efficiency

Concept



USV





Locomotion

Diferential Propulsion



Perception

Several sensors able to detect obstacles and environmental parameters



Autonomy

Able to accomplish missions based on georeferenced points while avoiding obstacles



UAV





Locomotion

Vmulti-rotor VTOL able to land on water



Perception

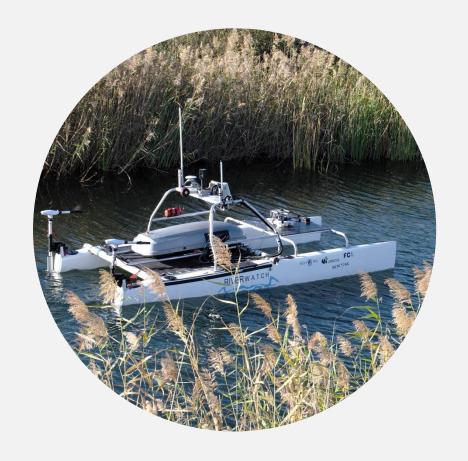
Equipped with Multispectral Cameras

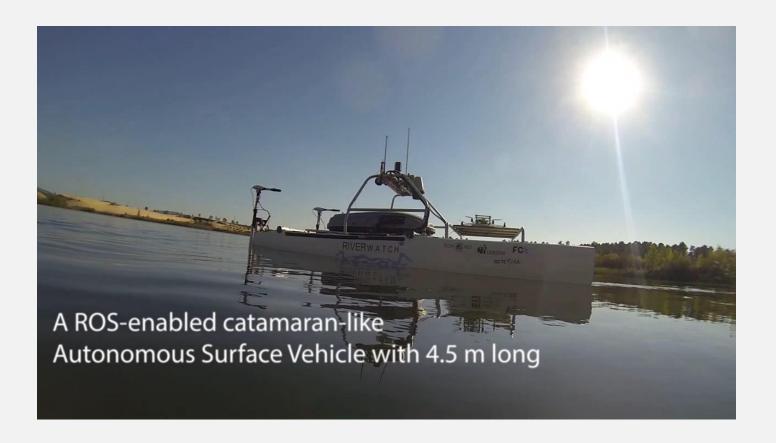


Autonomy

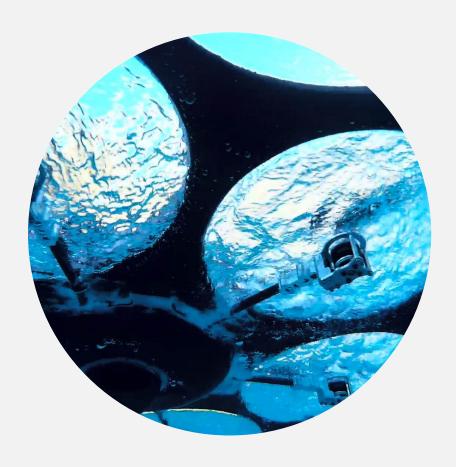
Able to follow geolocalised way points

The Team





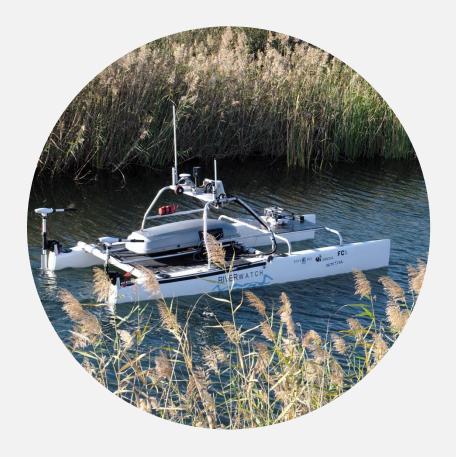
WVIGIL-R6 Development







Harbour Monitoring



Robotics Exercise with the Portuguese Navy



DRONES4GOOD – Migrants Detection



DRONES4RIGHT2LIFE

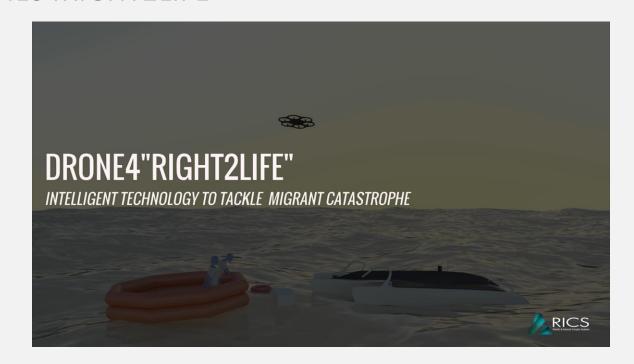
We participated in the 2017 Drones4good award as one of the 10 semi-finalists.

Drones4good is Mission Statement:

"The UAE Government invite the most innovative and creative minds to find solutions that will improve people's lives and provide positive technological solutions to modern day issues.

This Award is designed to offer the people of the world an opportunity to really make a difference. With a commitment underlined by the significant prize fund"

In 2017 the Competition received 1000 applications from 57 countries.



DRONES4GOOD – Migrants Detection



DRONES4RIGHT2LIFE





About Us



Mobile Autonomous Robotic Systems

Main Research Areas:

- Multi-Robots Collaboration using Shared Perception and Visual Attention: Applying these Developments to Difdferent Areas: Marine, Agriculture, Industry, ...

-Applying Field Robotics to Industry 4.0: eMerging the Two Different Research Areas Inside RICS.

MARS Team



Prof. José Barata Coordinator



André Lourenço

3D Perception



Eduardo Pinto

Hardware



Ricardo Mendonça

2D Perception



Francisco Marques

Navigation



Manuel Silva
Technician



Carlos Simões

Hardware



Pedro Prates

UAV Development



Luis do Ó

UAV Development

Developed Robots



Pelagi

ASV – Echord Riverwatch



Vigil R6

UAV, Echord Riverwatch, RoboSampler



Vigil WR6
Waterproof UAV



Vigil WR7 UAV - Finalist UAE 2017 Award Drone for Good



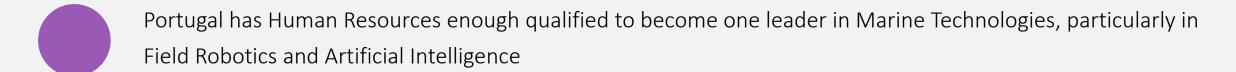


Helius R2



Helius R3

Final Thoughts



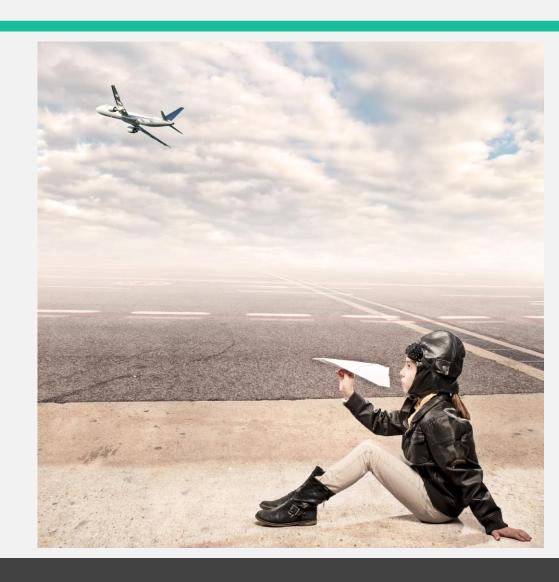
- But we need to make this goal an objective of the all Society
- For that we need to do things, we need to build our own systems, making mistakes, and YES, in some cases REINVENTING the WHEEL, if this brings experience to build different types of locomotion.

Companies, Universities, Research Centers, the NAVY need to cooperate to create the Sea Oriented Thinking, generating knowledge, creating products, and showing the Portuguese society what we are able to do.

Final Thoughts

The most difficult thing is the decision to act, the rest is merely tenacity. The fears are paper tigers. **WE** can do anything we decide to do. **WE** can act to change and make our dreams a reality; and the procedure, the process is its own reward.

Adapted from Amelia Earhart



Thank You

The most difficult thing is the decision to act, the rest is merely tenacity. The fears are paper tigers. You can do anything you decide to do. You can act to change and control your life; and the procedure, the process is its own reward.

For More Details Please Check rics.uninova.pt